# Fermi/GBM localizations of γ-ray bursts



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## **Neutrino or GW Counterpart Search**







IceCube tracks (1°) vs. showers (~15°)

#### Previous Fermi/GBM locations do not provide improvements, ...but this can be cured

Neutrino-Showe

Neutrino-track

3Lac Source

Abbott+2016, Living Rev. Relativity, 19, 1

# **GBM Detection:** Sky + Bkg + Earth + Sun





Each detector sees a certain relative fraction of sky (bkg and sources), Earth albedo or blockage, etc

This relative fraction changes with time At a given time, this fraction is different for each detector

25 years Konus-Wind, St. Petersburg, 9.-13.9.2019

# **Previous GBM localization performance**



• integrating this function to 95% containment implies  $2\sigma_{sys} \sim 16^{\circ}$ • only GRBs with statistical error  $\gg 16^{\circ}$ are not affected by systematics (=4%)

The problem: for a given GRB, we don't know to which of these two components it belongs?

 $\rightarrow$  So we have to adopt the large uncertainty for every GRB in order to be on the safe side (in terms of counterpart search)

# **GBM localization algorithm**



Principle: Relative response at different energies varies with off-axis angle

- So far: <u>same</u> spectral template spectrum is assumed for all (long/short) GRBs to compute model rates, and a position is derived via comparison to the relative observed rates in each detector on a 1° grid on the sky
  Connaughton+2015
- Previous Fermi/GBM (and CGRO/BATSE) method has large systematic error:

 $\succ$  Correct way: fit spectrum and position at the same time  $\rightarrow$  BALROG

## **Spectral templates for position determination**





with a built-in Pythonic user interface

dramatic effect on spectral parameters

# BALROG



Likelihood Model

 $\succ$ 

Burgess, Yu, Greiner (2016)

$$-2\log L = 2\sum_{i=1}^{N} \underline{M_i(\vec{\phi}, \vec{p})} + t_s f_i - D_i \log(\underline{M_i(\vec{\phi}, \vec{p})} t_s f_i) + \frac{1}{2\sigma_{B,i}^2} (B_i - t_s f_i)^2 - D_i (1 - \log D_i)$$



p=position,  $\Phi$ =spectral par.  $B_i$ =bkg cts,  $\sigma_{B,i}$ =Gaussian error in i<sup>th</sup> channel D<sub>i</sub>=observed total data cts

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# **BALROG results on GBM/Swift GRBs**



- Statistical errors about 30% larger, as they incorporate the location uncertainty
- Proof of concept against 115 Swift localized GRBs (2008-2018): For all the statistical  $3\sigma$  + systematic error contour includes the true position when  $\sigma_{sys} \sim 1^{\circ} (2^{\circ}) (s/c \text{ dep.})$
- Paradigm shift: problems since 1991 (CGRO/BATSE)

#### **Fermi/GBM Localizations**

#### Previous Fermi/GBM (and CGRO/BATSE) method has large systematic error: Connaughton+2015

#### Connaughton+2015 Last 30 years until present Th ("official" GBM team) with Follow-up search finds nothing! error t t $1\sigma_{stat}$ $1\sigma_{stat+sys}$ Real loc

This would be the correct way with the previous systematic







Example from real life: GRB 170705.115



25 years Konus-Wind, St. Petersburg, 9.-13.9.201!

## **Performance of the Automatic BALROG**

- ➤ 225 localizations computed in real-time since Nov. 1, 2018
- ➢ 38 have accurate localizations from Swift/MAXI/INTEGRAL/IPN
- Percentage of GRBs, containing the accurate position within their 1σ, 2σ or 3σ error region:



### **Consequences for follow-up**

Berlato+2019

#### Size of sky area reduces by substantial fraction:

- for 96% of GRBs where 2σ stat. < syst....
- ...the search regions would have to be inflated by 800 deg<sup>2</sup> (DoL) vs. 50 deg<sup>2</sup> (BALROG's systematics)
- ...96% of all DoL-localized GRBs come with inflated error region (only 4% have a statistical error larger than the DoL systematics)
- Smaller size also implies much less tiling by small(er)-FOV instruments
- Smaller size has substantially smaller number of false positives: ZTF finds roughly 3 variables per deg<sup>2</sup> per night!

#### Future: multi- $\lambda$ instruments

Wavelength	# src / □º	FOV	Sensitivity	instruments
γ-rays	0	++	-	Fermi/GBM, INTEGRAL/ACS, IPN
X-rays	2	+		Swift (tiling), MAXI
UV	10		-	-
Optical/NIR	1000	+	-	many
IR	50			-
Radio	2	_	-	LOFAR

 $\rightarrow$  Largest progress possible: with new, more sensitive  $\gamma$ -ray detector(s)

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# **Four Different Localization Methods**

Relative rates in different detectors cheap, but localization accuracy ≥1°

Relative arrival times at different detectors cheap, localization accuracy depends on detector size, time resolution and satellite distances

Coded mask large size, small field-of-view

Compton camera heavy and expensive



Fermi/GBM









GCN

- Rapid localization of source on celestial sphere
- Pointing of optical and other telescopes to identified position for detailed study

# **Summary**

- BALROG provides accurate localizations with ~10x smaller (systematic) error, primarily for strong GRBs
- $> \dots$  within ~30 min
- ...via GCN, or automatically after sign up at https://grb.mpe.mpg.de
- ...updated with TTE data after ~1-6 hrs (data availability) (just on Web-page; no GCNs)
- Most promising rapid (few years) route to better localizations: detectors somewhat bigger than Konus on interplanetary s/c

# Reply to M. Briggs / arXiv:1909.03006

- It is nice to see that 3 years after we suggested BALROG, the Huntsville team has finally recognized that their templates are a big problem, and now have changed them
- It is hard to understand why they still don't do the final step of fitting position and spectrum together
- It is nice to see that our publicly available BALROG code is used! Fairness implies that they make their code public as well.
- It is irritating to see that upon problems in using that code they don't dare to ask about clarifications, but submit a paper draft to arXiv with lots of strange (if not to say wrong) statements
- The plot shown by M. Briggs is irrelevant it is not the offset what counts, but its ratio to the quoted error! A GBM position should come with its appropriate statistical and systematic error, which has not been the case, and is still not the case for Huntsville-issued GCNs!